



# PRO Series Programmable Servo Drive







## Compact drive solution for rotary or linear brushless, stepper or PMDC brush motors.

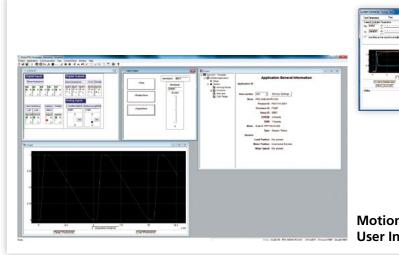
The ElectroCraft PRO Series Programmable Servo Drives are based on a new design concept offering a cost effective, compact and modular solution for the control of rotary or linear brushless, stepper or PMDC brush motors of powers up to 1600W, with 80V nominal voltage. Designed to support both low and high-volume applications, the ElectroCraft PRO Series drive integrates advanced motor control and motion control functionality in a single plug-in module

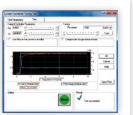
#### The drive can operate:

- As a single-axis motion controller, autonomously running the program residing in its non-volatile memory.
- As an intelligent slave executing motion sequences triggered by input lines.
- As a part of a multi-axis, distributed motion control solution in either standalone or slave configurations.
- As an intelligent slave executing motion sequences triggered by com-

mands received via RS-232, EtherCAT or CAN bus communication.

• Operating with Safe Torque Off, compatible with IEC 61800-5.2. 2 x STO inputs which when left unconnected, will disable motor outputs. This provides a dual redundant hardware protection that cannot be overridden by software or other hardware components.





MotionPRO Suite User Interface



The configuration, tuning and programming of the PRO-Ax0V80 drive is easy with ElectroCraft's powerful MotionPRO Suite user interface.

### • Fully digital servo drive suitable for the control of rotary or linear brushless, stepper or PMDC brush motors

- Very compact design
- Standard PCle 4x mating connectors (PE Versions)
- Sinusoidal or trapezoidal (Hall-based) control of brushless motors
- Open or closed-loop control of 2-phase stepper motors
- Various modes of operation, including: torque, speed or position control; position or speed profiles, external analogue reference or sent via communication bus
- Comprehensive motion instruction set for the definition and execution of motion sequences
- EtherCAT (CoE) in conformance with CiA402 device profile

### · .= ## Features \*\*\*\*

- R-232 serial communication
- CAN-Bus 2.0B up to 1 Mbit/s CANopen (CiA 301v4.2 and 402v3.0) protocols
- Dua I power supply: 12-80V; logic supply: 12-36V
- Digital and analogue I/Os:
  - 4 Digital inputs: 5-36V, NPN [Enable, 2 Limit switches, plus 2 general purpose]
  - 4 Digital outputs: 5-36V, NPN or PNP [Ready, Error, plus 2 general purpose]
- 2 Analogue inputs: 12-bit, 0-5V and ±10V [Reference, Feedback or general-purpose]
- Standalone operation with stored motion sequences

- Hardware protections: short-circuit (between motor phases and from motor phases to GND), over-voltage, under-voltage and I<sup>2</sup>t
- Switching Frequency up to 60kHz
- Operating ambient temperature: 0-40°C
- Feedback devices supported:
  - Incremental quad encoder (single-ended, open collector and differential)
  - Analogue sine/cosine incremental encoder (differential 1Vpp)
  - Digital Hall sensors or sensorless communication
  - Support for absolute feedback (SSI, BiSS, EnDAT and resolver)
  - Dual encoder input supported for dual loop control



# • Specifications

Flexibility – Control schemes supported by the PRO-A04V36x Drive							
Motor Types (rotary or linear) Torque Control Speed Control Position Control							
Brushless	✓	✓	✓				
Stepper	✓	✓	✓				
PMDC Brush	✓	✓	✓				

Ordering Information				
PRO-A10V80A-SA-CAN	Stand-alone Programmable Drive (80V, 10A, 800W, Enc., CAN)			
PRO-A10V80A-SA-CAT	Stand-alone Programmable Drive (80V, 10A, 800W, Enc., CAT)			
PRO-A20V80A-SA-CAN	Stand-alone Programmable Drive (80V, 20A, 1600W, Enc., CAN)			
PRO-A20V80A-SA-CAT	Stand-alone Programmable Drive (80V, 20A, 1600W, Enc., CAT)			
500500	MotionPRO Suite User Interface Software			

Motor – sensor configurations					
Motor Types	Brushless	Stepper (2-phase)	PMDC Brush		
Incr. Encoder	✓	✓	✓		
Incr. Encoder + Hall	✓				
Analog Sin/Cos encoder	✓				
Linear Halls	✓				
Tacho			✓		
Open-loop (no sensor)		✓			

NOTE: SSI, EnDAT, BiSS encoders and Resolver feedback is possible with an additional feedback

Conditions					
Operating		Min.	Тур.	Max.	Units
Ambient Temperature <sup>1</sup>		0		+40	°C
Ambient Humidity	Non-condensing	0		90	%rh
Altitude / Pressure <sup>2</sup>	Altitude (vs. sea level)	-0.1	0-2.5	2	Km
	Ambient Pressure	O <sup>2</sup>	0.75-1	10.0	atm
Storage		Min.	Тур.	Max.	Units
Ambient Temperature		-40		+85	°C
Ambient Humidity	Non-condensing	0		100	%rh
Ambient Pressure		0		10.0	atm

 $<sup>^1</sup>$  Operating temperature can be extended up to +65°C with reduced current and power ratings.  $^2$  PRO-Ax0V80 can be operated in vacuum (no altitude restriction), but at altitudes over 2,500m, current and power rating are reduced due to thermal dissipation efficiency.  $^3$  For all values, PRO-A10V80 (PRO-A20V80)

Electrical Specifications						
Maximum DC Supply Voltage	Motor	80	volt			
Maximum DC Supply Voltage	Logic	36	volt			
Maximum continuous current <sup>3</sup>	Peak of sine	10 (20)	amp			
Maximum continuous current	RMS	7.07 (14.1)	amp			
Park 12 4	Peak of sine	20 (40)	amp			
Peak current (2.4 sec. max.)	RMS	7.1	amp			
Nominal switching frequency	14.1 (28.2)	kHz				

Input						
Logic Supply Input (+V <sub>LOG</sub> )		Min.	Тур.	Max.	Units	
	Nominal values	9		36	V <sub>DC</sub>	
Supply	Absolute maximum values, drive operating but outside guaranteed parameters	8		40	V <sub>DC</sub>	
Voltage	Absolute maximim values, continuous	-0.6		42	V <sub>DC</sub>	
	Absolute maximum values, surge (duration ≤ 10ms) <sup>†</sup>	-1		+45	V	
	+V <sub>LOG</sub> = 9V		300		mA	
Supply	+V <sub>LOG</sub> = 12V		250			
Current	+V <sub>LOG</sub> = 24V		150			
	+V <sub>LOG</sub> = 40V		100			
Motor Supp	oly Input (+V <sub>MOT</sub> )	Min.	Тур.	Max.	Units	
	Nominal values	12	80	90	V <sub>DC</sub>	
Supply	Absolute maximum values, drive operating but outside guaranteed parameters	11		94	V <sub>DC</sub>	
Voltage	Absolute maximim values, continuous	-0.6		94	V <sub>DC</sub>	
	Absolut maximum values, surge (duration ≤ 10ms) <sup>†</sup>	-1		95	V	
Supply Current	Idle		1	5	mA	
	Operating	-20 (-40)	±10 (±20)	20 (40)	А	
	Absolute maximum value, short-circuit condition (duration ≤ 10ms) <sup>†</sup>			22.5 (45)	А	

Output						
Motor Outputs (A/A+, B/A-, C/B+, BR/B-)			Min.	Тур.	Max.	Units
Nominal	DC brushed, steppers and BLDC motors with Hall-based trapezoidal control				10 (20)	
output current,	Brushless motors with sinusoidal control (sinusoidal amplitude RMS value)				10 (20)	А
continuous <sup>3</sup>	Brushless motors with (sinusoidal effective RI				7.07 (14.2)	
Motor out- put current, peak <sup>3</sup>	maximum 10s (3.6)		-20 (-40)		+20 (+40)	А
Short-circuit protection threshold <sup>3</sup>	measurement range				± 22.5 (± 45)	А
Short-circuit protection delay			5	10		μS
On-state voltage drop	Nominal output current; including typical mating connector contact resistance			±0.3	±0.5	V
Off-state leakage current				±0.5	±1	mA
Motor inductance (phase to phase)	Recommended value, for current ripple max. ±5% of full range;	F <sub>PWM</sub>				
		20 kHz	330			μН
		40 kHz	150			μп
	+V <sub>MOT</sub> = 36 V	60 kHz	120			



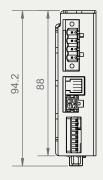


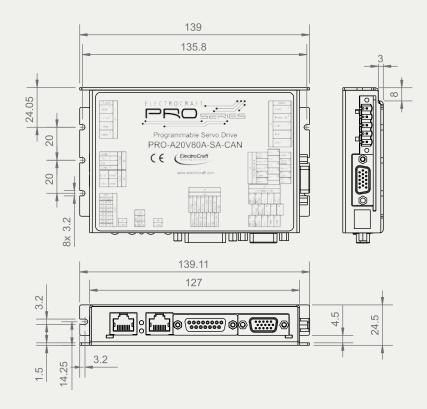


#### PRO-A20V80A-SA-CAN

Height: 24.5 mm Width: 94.2 mm Length: 139 mm

All dimensions are in mm. Drawings not to scale.





### PRO-A20V80A-SA-CAT

Height: 24.5 mm Width: 94.2 mm Length: 139 mm

All dimensions are in mm. Drawings not to scale.

